



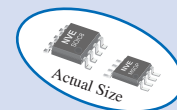
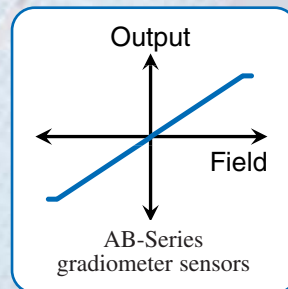
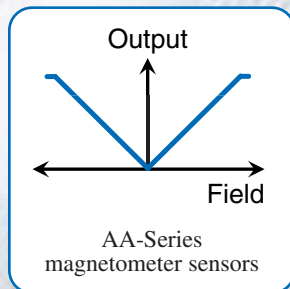
NEW!
Rotation
Sensors

Magnetic Sensors *Short-Form Catalog*

AA and AB-Series Analog Sensors

Versatile, Sensitive, and Accurate

Versatile AA and AB-Series analog GMR sensors are ideal for a wide range of analog sensing including industrial and automotive position, speed, and current sensors. A Wheatstone bridge configuration compensates for temperature and power supply variations. The devices are offered in SOIC8 and MSOP8 packages.



AA-Series sensors are magnetometers, sensitive in the plane of the device. The output is omnipolar, providing same output for magnetic fields in either direction.

AB-Series sensors are differential devices, or gradiometers, with the bipolar linear output characteristics of a differential sensor.

H-type magnetometer and gradiometer versions offer extremely high sensitivity for low-field applications.

Part Number	Saturation (Oe)	Linear Range (Oe)		Sensitivity (mV/V-Oe)		Typical Resistance	Package
		Min.	Max.	Min.	Max.		
AAH002-02	15	0.6	3	11	18	2 K Ω	SOIC8
AA002-02	15	1.5	10.5	3	4.2	5 K Ω	SOIC8
AA003-02	20	2	14	2	3.2	5 K Ω	SOIC8
AA004-00	50	5	35	0.9	1.3	5 K Ω	MSOP8
AA004-02	50	5	35	0.9	1.3	5 K Ω	SOIC8
AA005-02	100	10	70	0.45	0.65	5 K Ω	SOIC8
AA006-00	50	5	35	0.9	1.3	30 K Ω	MSOP8
AA006-02	50	5	35	0.9	1.3	30 K Ω	SOIC8

Magnetometer selection guide

Part Number	Saturation (Oe)	Linear Range (Oe)		Element Spacing (mm)	Typical Resistance	Package
		Min.	Max.			
AB001-02	250	20	200	0.5	2.5 K Ω	SOIC8
AB001-00	250	20	200	0.5	2.5 K Ω	MSOP8
ABH001-00	70	5	40	0.5	1.2 K Ω	MSOP8

Gradiometer selection guide

Gear-Tooth Sensors

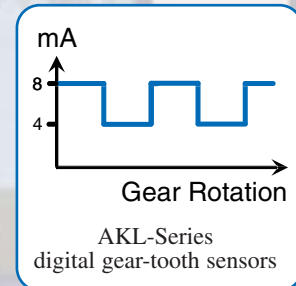
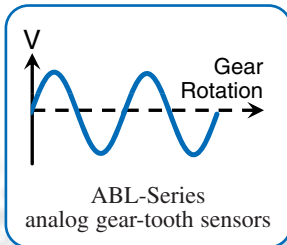
Small and Robust



ABL and AKL-Series are versatile, wide air gap gear-tooth sensors. The sensors are used with ferromagnetic gears and bias magnets, or with magnetic encoders.

ABL-Series analog sensors have differential sensor elements that provide sinusoidal outputs. Three standard spacings are available for use with fine and coarse pitches. Single- or double-bridge configurations are available. Double bridges generate sine and cosine outputs to provide direction information.

AKL-Series sensors are digital parts are configured as two-wire devices, where the supply current indicates a passing tooth. Three AKL-Series parts are available: the AKL001-12 is designed for gear teeth or encoders with a pitch of 2.5 to 6 mm, the AKL002-12 for a pitch of 1 to 2.5 mm, and the AKL003-12 for a pitch of 0.6 to 1.5 mm.



Part Number	Single or Dual Bridge	Element Spacing (mm)	Package
ABL004-00	Single	1	MSOP8
ABL005-00	Single	0.5	MSOP8
ABL006-00	Single	0.3	MSOP8
ABL014-00	Dual	1	MSOP8
ABL015-00	Dual	0.5	MSOP8
ABL016-00	Dual	0.3	MSOP8
ABL004-10	Single	1	TDFN6
ABL005-10	Single	0.5	TDFN6
ABL006-10	Single	0.3	TDFN6
ABL014-10	Dual	1	TDFN6
ABL015-10	Dual	0.5	TDFN6
ABL016-10	Dual	0.3	TDFN6

ABL-Series selection guide

Part Number	Single or Dual Bridge	Element Spacing (mm)	Package
AKL001-12	Single	1	TDFN8
AKL002-12	Single	0.5	TDFN8
AKL003-12	Single	0.3	TDFN8

AKL-Series selection guide

GMR Switch Digital Sensors

Sensitive and Precise

GMR Switch Precision Digital Sensors provide more precise operate points than Hall-effect or other conventional sensors.

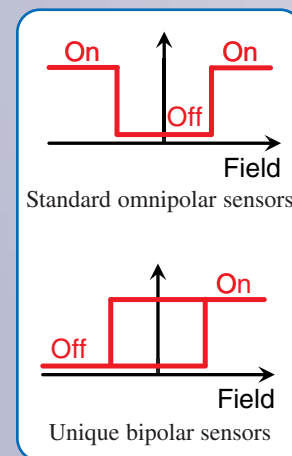
AD-Series digital sensors are available with a variety of switch points and output configurations, and come in TDFN and MSOP packages. The parts have a wide 4.5 to 30 volt supply range.

Standard AD-Series sensors are omnipolar, so a field of either polarity switches the sensor ON, and the sensor turns OFF when the field is removed. However the unique ADV001 sensor is bipolar (south field ON, north field OFF).

AFL-Series sensors have a 0.9 to 5.5 volt supply range for low-voltage and battery-powered applications.

Part Number	Typ. Operate Point (Oe)	Supply Voltage Range	Typ. Supply Current (mA)	Output Type	Package
AD004-00	20	4.5 V – 30 V	3.5	Sink	MSOP8
AD005-00	40	4.5 V – 30 V	3.5	Sink	MSOP8
AD021-00	20	4.5 V – 30 V	3.5	Sink	MSOP8
AD022-00	40	4.5 V – 30 V	3.5	Sink	MSOP8
AD024-00	28	4.5 V – 30 V	3.5	Sink	MSOP8
AD024-10	28	4.5 V – 30 V	3.5	Sink	TDFN6
AD621-00	20	4.5 V – 30 V	3.5	Sink+Source	MSOP8
AD824-00	28	4.5 V – 30 V	3.5	2 Sinks+SCP	MSOP8
ADH025-00	11	4.5 V – 30 V	3.5	Sink	MSOP8
ADV001-00	±4	4.5 V – 30 V	3.5	Bipolar; Sink	MSOP8

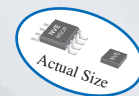
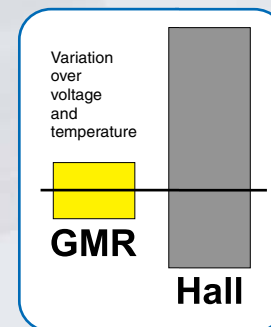
Popular AD-Series digital sensors



Part Number	Typ. Operate Point (Oe)	Supply Voltage Range	Output Type	Package
AFL000-10E	10	0.9 V – 1.3 V	Normally Off, Current Sink	TDFN6
AFL000-01	10	0.9 V – 1.3 V	Normally Off, Current Sink	Die
AFL002-10E	28	0.9 V – 1.3 V	Normally Off, Current Sink	TDFN6
AFL020-00E	10	0.9 V – 1.3 V	Normally On, Current Source	MSOP8
AFL030-00E	10	0.9 V – 1.3 V	Normally Off, Current Source	MSOP8
AFL100-00E	10	1.8 V – 2.5 V	Normally Off, Current Sink	MSOP8
AFL100-10E	10	1.8 V – 2.5 V	Normally Off, Current Sink	TDFN6
AFL103-01	40	1.8 V – 2.5 V	Normally Off, Current Sink	Die
AFL200-00E	10	2.7 V – 3.6 V	Normally Off, Current Sink	MSOP8
AFL300-00E	10	4.5 V – 5.5 V	Normally Off, Current Sink	MSOP8

AFL-Series digital sensor selection guide

Benefits:	GMR	Hall	AMR	Reed
Size	Small	Small	Large	Very Large
Signal Level	Large	Small	Medium	Switch
Sensitivity	High	Low	High	Low
Temperature	High	Low	Medium	Medium
Power	Low	Low	High	Switch
Cost	Low	Low	High	Low



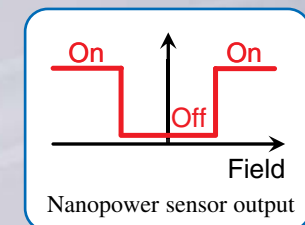
Nanopower Sensors

Ultraminiature; Ultralow Power



Small enough to fit on the head of a pin and low enough power to run indefinitely on a button cell, NVE Nanopower Magnetic Switches provide the ultimate in miniaturization and low power. Internally duty-cycled versions reduce power consumption to nanowatts. The sensors are available with a variety of operate points and come in a tiny 1.1 x 1.1 mm ULLGA package.

ADL-Series sensors have a 2.4 to 3.6 volt supply range; the AHL-Series uses 0.9 to 2.4 volts.



Part Number	Typ. Operate Point (Oe)	Supply Voltage Range	Typ. Supply Current (µA)	Typ. Update Frequency	Package
ADL021-14E	20	2.4 V – 3.6 V	0.08	55Hz	ULLGA
ADL022-14E	40	2.4 V – 3.6 V	0.08	55Hz	ULLGA
ADL024-14E	28	2.4 V – 3.6 V	0.08	55Hz	ULLGA
ADL121-14E	20	2.4 V – 3.6 V	0.03	30Hz	ULLGA
ADL122-14E	40	2.4 V – 3.6 V	0.03	30Hz	ULLGA
ADL124-14E	28	2.4 V – 3.6 V	0.03	30Hz	ULLGA
ADL921-14E	20	2.4 V – 3.6 V	35	Continuous	ULLGA
ADL922-14E	40	2.4 V – 3.6 V	35	Continuous	ULLGA
ADL924-14E	28	2.4 V – 3.6 V	35	Continuous	ULLGA
AHL021-14E	20	0.9 V – 2.4V	0.095	110Hz	ULLGA
AHL024-14E	28	0.9 V – 2.4V	0.095	110Hz	ULLGA
AHL025-14E	10	0.9 V – 2.4V	0.095	110Hz	ULLGA
AHL921-14E	20	0.9 V – 2.4V	35	Continuous	ULLGA
AHL924-14E	28	0.9 V – 2.4V	35	Continuous	ULLGA
AHL925-14E	10	0.9 V – 2.4V	35	Continuous	ULLGA

Nanopower sensor selection guide

Angle and Rotation Sensors

Small, Accurate, and Ultralow Power

AAT and ADT-Series noncontact angle and rotation sensors are based on spintronic Tunneling Magnetoresistance (TMR) elements for small size, large signals, and low power. An external magnet provides a saturating magnetic field in the plane of the sensor. The sensors tolerate a wide magnetic field range of 30 to 200 Oe. Parts are packaged in NVE's 2.5 x 2.5 x 0.8 mm TDFN6 package.

AAT-Series angle sensors provide sine and cosine signals defining the angle of rotation. Outputs are proportional to the supply voltage and peak-to-peak output voltages are much larger than conventional sensor technologies. Available bridge resistances range from the AAT009, with a typical device resistance of 6 megohms for ultralow power, to the AAT003 with a 40 kilohm typical device resistance (20 kilohm output impedances) for direct interface to simple microcontrollers while retaining low power.

The ADT-Series rotation sensors have two digital, binary outputs. The outputs are 90 degrees out of phase to provide directional information. The ADT001 is high hysteresis for high noise immunity in applications such as speed sensing; the ADT002 is low hysteresis to provide accurate, absolute rotational quadrant information.

Key features of AAT- and ADT-Series sensors are:

- Extremely low power
- Wide airgap tolerance
- Wide supply range
- -40°C to +125°C operating range
- Ultraminiature TDFN6 package

Popular applications include:

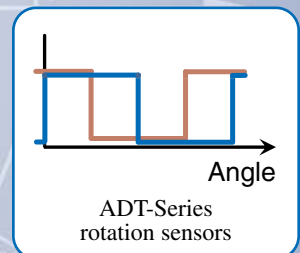
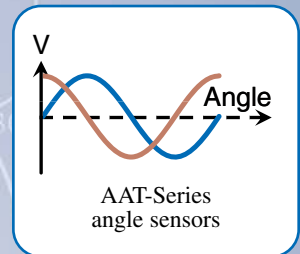
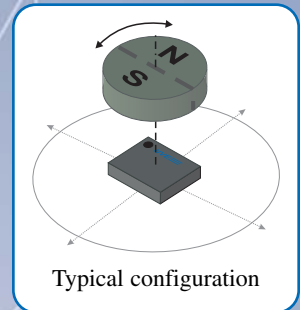
- Rotational position sensors
- Rotational speed sensors
- Water meters

Part Number	Typ. Output (ea. output; p-p)	Max. Error (const. field)	Typ. Device Resistance	Package
AAT001-10E	200 mV/V	0.5°	1.25 MΩ	TDFN6
AAT003-10E	200 mV/V	0.5°	40 KΩ	TDFN6
AAT009-10E	200 mV/V	0.5°	6 MΩ	TDFN6

AAT-Series angle sensor selection guide

Part Number	Max. Error (const. field)	Typ. Hysteresis	Typ. Supply Current	Package
ADT001-10E	0.5°	20°	2.5 μA	TDFN6
ADT002-10E	0.5°	4°	2.5 μA	TDFN6

ADT-Series rotation sensor selection guide



Angle	Output	
	Sin	Cos
0°-90°	H	H
90°-180°	H	L
180°-270°	L	L
270°-360°	L	H

ADT-Series rotation sensor truth table

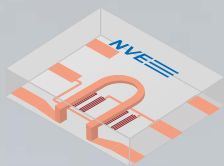
Current Sensors

Small, Precise, and Low Power

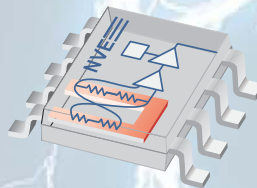
NVE's current sensors use GMR sensor elements using unique, bipolar output low-hysteresis GMR materials for AC or DC measurements. Output voltages are proportional to the current through on-chip straps and ratiometric with the supply voltage.

The AAV003 has a -80 to $+80$ milliamp measurement range and a high-sensitivity bridge output. The part is packaged in a 2.5×2.5 mm TDFN6 package.

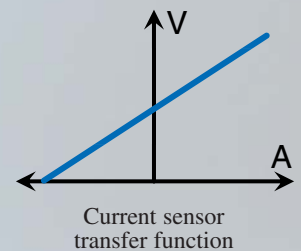
The AAV004 range is -5 to $+5$ amps, and includes on-chip signal processing to temperature compensate and amplify the output with a rail-to-rail output. An on-chip EEPROM stores temperature and linearity factory calibration data. The AAV004 is packaged in a small-footprint SOIC8 package, and the output is fully isolated from the input in accordance with UL and VDE high-voltage standards.



The AAV003 current sensor



The AAV004 current sensor

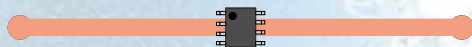


Part Number	Measurement Range	Sensitivity (mV/V/A)	Package
AAV003-10E	± 80 mA	80	TDFN6
AAV004-02E	± 5 A	100	SOIC8

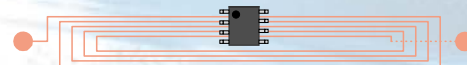
Current sensor selection guide

In addition to dedicated current sensors, NVE AA-Series Analog Sensors (see page 2 of this catalog) are often used to measure the current over an external circuit board trace, particularly for overcurrent protection where high accuracy is not required. The sensor measures the current by detecting the magnetic field generated by the current through the trace.

Typical configurations are shown below:



0.09" trace (3.5 mV/V/A with AA003 sensor)



7 x 0.008" trace (20 mV/V/A with AA003 sensor)

The AA003-02 is popular for this application, but other AA-Series sensors can be used depending on required sensitivity.

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On the Cover

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